## EC MACHINE DIRECTIVE COMPUANCE DECLARATION

(DIREC TIVE 89/392 EEC, APPENDIX II, PARTB)

Manufacturer: FAAC S.p.A.
Address: Via Benini, 1
40069-Zola Predosa
BOLOGNA - ITALY
Hereby declares that the 959 B-E automation system

- isintended to be incorporated into machinery, orto be a ssembled with other machinery to constitute machinery in compliance with the requirements of Direc tive 89/392 EEC, and subsequent a mend ments 91/368 EEC, 93/44 EEC and 93/68 EEC;
- complieswith the essential safety requirementsin the following EEC Directives:

73/23 EEC and subsequent a mendment 93/68 EEC.
89/336 EEC and subsequent amendments 92/31 EEC and 93/68 EEC.
and furthermore declares that unit must not be put into service until the machinery into which it is incorporated or of which it is a component has been identified and declared to be in conformity with the provisions of Direc tive 89/392 EEC and subsequenta mendmentsena cted by the national implementing legislation.

Bologna, 1 J anuary 1997


## IMPORTANTNOTICE FOR THE INSTAUER

## GENERALSAFETY REGULATIONS

1) WARNING! FAAC strongly recommends to follow these instructions literally for the safety of persons. Improper installation or misuse of the product will cause very serious damages to persons.
2) Packaging material (plastic, polystyrene etc.) is a potential hazard and must be kept out of reach of children.
3) Read the instructions carefully before installing the product.
4) Keep these instructions for future reference.
5) Thisproduct hasbeen designed and manufactured only for the use stated in this manual. Any otheruse not expressly set forth will affect the reliability of the product and/or could be source of hazard.
6) FAAC S.p.A. cannot be held responsible forany da mage caused by improper use ordifferent from the use for which the automation system is destined to.
7) Do not use this device in areas subject to explosion: the presence of flammable gas or fumes is a serioushazard.
8) Mechanical constructive elements must comply with CEN pr EN 12650-1 and CEN pr EN 12650-2 standards.

Countriesoutside the EC shallfollow the regulationsabove besidestheirna tionalnormative referencesin orderto offer the utmost safety.
9) FAAC cannot be held responsible forfailure to observe technical standards in the construction of gates and doors, or for any deformation of the gates which may occur during use.
10) Before camying out any operations, tum off the system's ma in switch.
11) An omnipowerswitc $h$ shall be provided forthe installation with an opening distance of the contactsof 3 mm ormore. Altematively, use a 6A themomagnetic breaker with multi-pole switc hing.
12) Ensure that there is a differential switch up-line of the electric al system, with a trip threshold of 0.03A.
13) Check that the earthing plant is in perfect condition and connect it to the metallic parts. Also earth the yellow/green wire of the operator.
14) The a utomation is fitted with an anti-crush safety system that is a torque control device. In any case, further safety devic es shall be installed.
15) The safety devices(e.g. photocells, safety edges, etc.) protect areaswherethere isa mechanic almovement hazard, e.g. crushing, entrapment and cutting.
16) Each installation must be fitted with at least one waming plate suitably fixed to the gate, besidesthe safety devices as per point 15. above.
17) FAAC cannot be held responsible regarding safety and correct functioning of the a utomation in the event that parts other than FAAC original parts are used.
18) Use only FAAC original spare parts for maintenance operations.
19) Do not cary out any modific a tions to a utomation components.
20) The insta llermust supply all information regarding ma nual operation of the system in the event of an emergency and provide the end-user with the leaflet attached to the product.
21) Keep out of persons when the product is in operation.
22) Keep out of reach of children the remote radio controlsand any control devices. The a utomation could be operated unintentionally.
23) The end-usermust a void any attempt to repairoradjust the automation personally. These operationsmust be caried out exclusively by qualified personnel.
24) What is not explicitly stated in these instructions is not permitted.

The 959 B-E automatic unit for swing doors is a one-piece unit consisting of an electromechanical device that allows door opening to be controlled by means of a driving a m.
The operatorcan be installed eitheron the linteloron the door structure itself.
The aluminium protective casing housesthe electronic control unit used to program and control the operation of the system. In the event of a power failure the door can be pushed (or pulled) open manually.

## 1. DESCRIPIION AND TECHNICALCHARAC TERISIICS



Fig. 1
(1) Cable hole
(6) Drive system
(2) Support profile
(7) $D C$ motor
(3) 959 MP electronic control unit
(8) $959 \mathrm{~B}-\mathrm{E}$ programming unit
(4) Position monitoring microswitch
(9) Protective casing
(5) Transmission shaft
(10) Operating function switch
(6) Transmission shaft
(11) End cover (2)

Table 1: Technical spec ifications of 959 B-E Operator

| Powersupply | $230 \mathrm{Vac}(+6-10 \%)-50$ (60) Hz |
| :---: | :---: |
| Absorbed power | 100 W |
| Currentdrawn | 0.5 A |
| Electric motor | 24 Vdc with encoder |
| Dimensions | $530 \times 100 \times 104$ (length $\times$ height $\times$ depth) |
| Weight | 10 kg |
| Ambienttemperature | $-15+70^{\circ} \mathrm{C}$ |
| Housing protection | IP 23 |
| Dimensionsand max. weightofleaf | see Table 3 (section 1.1) |
| Dutycycle | continuous |
| Operation in event of powerfailure | Manualpush/pullopening |
| Configuration ofdriving ams | - pushing articulated am (version for ja mb depth $0 \div 125 \mathrm{~mm}$ ) <br> - pushing articulated arm (version for ja mb depth $126 \div 250 \mathrm{~mm}$ ) <br> - sliding a m |
| Anti-crushing device | standard |
| Opening angle | $70 \div 95^{\circ}$ |
| Opening time | $3.5 \div 10 \mathrm{~s}$ (adjustable) |
| Closing time | $6 \div 13 \mathrm{~s}$ (adjustable) |

Table 2: Technical specifications of 959MP Electronic Control Unit + 959 B-E Programming unit

\begin{tabular}{|c|c|}
\hline Powersupply \& \(230 \mathrm{Vac}(+6-10 \%)-50(60) \mathrm{Hz}\) \\
\hline Accessoriespowersupply \& \(24 \mathrm{Vdc} / 500 \mathrm{~mA} \mathrm{max}\). \\
\hline Electric lock powersupply (N.O./N.C.) \& \(24 \mathrm{Vdc} / 0.5 \mathrm{~A} \mathrm{max}\). \\
\hline Standard operating functions(switch) \& Open / Automatic / Manual (Night) \\
\hline Adjustable functions(trimmer) \& Opening speed - Closing speed Pulling force - Pa use time \\
\hline \begin{tabular}{l}
Selectable functions(microswitches) \\
Standa
\end{tabular} \& Overc losing stroke non-standard initia lisation procedure h and Go-Function switch (pos. "0") \\
\hline Terminalstrip outputs

(N.O. \& Ma lfunction ala m signal24 Vdc electric lock powersupply .) - 24 Vdc accessoriespowersupply <br>
\hline Terminal strip inputs

STO \& | Function switch/CODIS(optional)- |
| :--- |
| Intemal/ extemal/ emergency/ |
| fety device / CLOSURE safety device | <br>

\hline
\end{tabular}

### 1.1 APPUCATION UMITS

Important To ensure correct application of the FAAC 959 B-E unit the weight of the doormust not exceed the value given in Table 3 corresponding to its length.
The maximum length of the leaf is 1000 mm .
The values of maximum weight vary according to the driving arm used.
Foreach driving arm there isalso a different maximum value for the depth of the doopost (Table 4) beyond which it is not possible to install the system correctly.

Table 3: Applic ation limits of 959 B-E automatic unit

| Length of leaf <br> $(\mathbf{m m})$ | Max. weight of leaf <br> $\mathbf{( k g )}$ <br> Pushing articulated am | Max. weight of leaf <br> $\mathbf{( k g )}$ <br> Sliding am |
| :---: | :---: | :---: |
| 700 | 130 | - |
| 750 | 124 | - |
| 800 | 118 | 92 |
| 850 | 113 | 89 |
| 900 | 108 | 85 |
| 950 | 104 | 83 |
| 1000 | 100 | 80 |

Table 4: Max. depth of doomost

|  | Pushing <br> articulated am <br> (Var. 01) | Pushing <br> articulated amm <br> (Var. 02) | Sliding am |
| :---: | :---: | :---: | :---: |
|  | $0-125$ | $126-250$ | $0-160$ |

## 2. ELEC TRICAL SEIUP (fig. 2a Standard system)

(1) 959 B-E operator
(2) Microwave radar/ Passive infrared sensor
(3) TZOE external key-switch (KEY command)
(4) Emergency Closing/Opening pushbutton
(5) CODIS programming unit (optional)
(6) CODIS inhibition switch (optional)
(7) 24 Vdc electric lock
(8) Junction box

If the operator is installed on the door, make the electrical connections using a junction box and suitable commercially available pipes/unions (fig. 2b).
N.B.: 1) Forinstallation of electrical ca bles use suita ble rigid or flexible piping.
2) Alwayskeep the low voltage ac cessory connection cables separate from the 230 V power cables. Use separate sheaths to avoid any interference.

## 3. INSTAШATION

### 3.1 PREUMINARY CHECKS

To ensure correctopera tion of the a utomatic unit the structure of the existing door must meet the following requirements:

- length and weight as specified in Table 3 (section 1.1);
- max. doomost depth as specified in Table 4;
- robust and rigid struc ture of the leaf;
- good condition of the existing hinges;
- smooth, uniform movement of the leaf with no abnomal friction at a ny point of its travel;
- "neutral" position of the door during its entire travel. If the door tends to close or open, check the alignment of the hinges.
- Presence of mechanical end stops.


### 3.2 MOUNTING THE OPERATOR

1) Remove the protective casing (fig. 3) a nd the end covers (fig. 4) from the operator.
Waming: Before removing the end cover with the function switch, remove the connector joining the switch to the 959MP electronic control unit.
2) As regards the mounting position of the operator (on the lintel or on the door) and the type of a m to use (pushing, pulling orsliding), referto the relevant mounting table and drill the holes required to mount the operator and the pulling a m.
N.B.: The two intemediate operator fixing holes a re not in a central position (see mounting tables). The holes are offset in order to ensure that the operator is mounted with the correct direction of rotation of the mechanism.

The mounting tables are the following:

## Table A: UNTEL MOUNTING (PUSHING ARIICULATED ARM) Outward opening

Table B: DOOR MOUNTING (PUSHING ARIICULATED ARM) Inward opening
Table C: UNTEL MOUNTING (SUDING ARM) Inward opening
3) Mount the operator using the six M6 screws a nd wa shers provided.

## Waming:

- The structure of the lintel (or the door) at the operator mounting position must not exhibit any significant deformation.
- The operator must be mounted parallel to the floor.
N.B.: If the sliding arm is to be used, the driving arm must be mounted before the operator is fixed on the lintel (see section 3.3.3.).


### 3.3 MOUNTING THE DRIVING ARMS

### 3.3.1 MOUNTING THE PUSHING ARTICULATED ARM (fig. 5)

1) Close the door.
2) Free ams (1) and (2) by pulling a part the coupling (3) manually as shown in fig. 5.
3) Fit a m (1) on the operator transmission shaft by means of the extension and the screw (4) provided (fig. 5). The arm must be mounted perpendicular to the closed door.
N.B.: If a greater distance between the operator and the a m is required, use the higherextensions a vaila ble as a ccessories (see Table A/B).
4) Mount plate (5) of arm (2) on the doororthe lintelusing the two M6 screws and the washers provided (fig. 5). The
installation distances a re given in Table A/B.
5) Slacken the fixing screw (6) a nd a ssemble the two a mmsby mea ns of coupling (3) (fig. 5).
6) Tum arm (1) until arm (2) is perpendicular to the closed door or the lintel as shown in fig. 5 (a-b), sliding the spacer (7) a long amm (2).
7) Tighten the fixing screw (6) between the two arms. The length of a m (2) is given in the relevant mounting tables. If necessary, c utoffthe section of the a mextend ing beyond the a rtic ulation and then coverthe endsusing the capsprovided (fig. 5).
8) Check manually that the door is free to open and close fully a nd tha t it comesto rest aga inst the mec hanical end stops. If the doordoesnot c lose c orrectly, adjust the retum spring a s described in section 10.

### 3.3.2 MOUNTING THE SUDING ARM (fig. 6)

1) Mountam(1) on the operatortransmission shaft bymeans of the extension and the screw (2) provided (fig. 6). The arm must be fitted pointing $45^{\circ}$ outwards as shown in fig. 6(a).
N.B.: If a largerdistance is required between the operatora nd the a rm use the higherextensionsa va ilable a sac cessories(see Table C).
Waming: Mount a m (1) on the tra nsmission shaft before fitting the opera tor on the lintel (fig. 6).
2) Insert the roller (3) inside the sliding guide (4) (fig. 6).
3) Pull a rm (1) inwards manually as shown in fig. 6(b) and secure the sliding guide (4) by mea ns of two M6 sc rews on the closed door as shown in Table $C$.
4) Check manually that the door is free to open and close fully a nd comesto rest a ga inst the mec ha nic al end stops. If the doord oesnot close correctly, adjust the retum spring as desc ribed in section 10 .

## 4. START-UP

1) Make the electrical connectionsto the 959 MP electronic control unit as desc ribed in section 6.
To gain accessto the control unit, passthe cablesthrough the special conduit (fig. 1 - ref. 1) as shown in fig. 8.
2) Fitthe two end coversa nd connect up the function switch. The end coverwith the switch may be fitted on the right or the left. For cable routing refer to fig. 8.
3) Tum the operating function switch (fig. 1 - ref. 12) to position I (AUIOMATIC logic).
4) Check that the programming unit mic roswitches (fig. 10) are all in the OFF position.
Important When mounting the "pulling a rtic ulated" or"sliding" arms or for opening a ngles greater than $90^{\circ}$, tum mic roswitch no. 2 to ON before connecting power to the system.
5) Close the door.
6) Powerup the operator. Powering issignalled by a $n$ a coustic signal from a buzzer.
7) Check that the 5V LED on the programming unit (fig. 9) lights up.
8) At the end of the initialisa tion procedure, check the status of the signa lling LEDs on the progra mming unit a sshown in Table 5.

Table 5: Operation of status LEDs

| IED | ON | OFF |
| :--- | :--- | :--- |
| 5V | logic powered | logic not powered |
| OK | command active | command inactive |
| YES | safety devices active | safety devices inactive |

N.B.: The statusof the LEDs with the doorclosed at rest is shown in bold type.

### 4.1. INITIALSATION PROCEDURE

As soon as the system is powered up, it runs an initialisation procedure which includes setting the following parameters:

- measuring the mass of the door;
- determining the end stop positions;
- determining the point at which the STOP safety device intervenes (see section 6).
The door opens at low speed, then closes half way before switc hing back to opening.
Subsequent closure is performed by the retum spring.
The initialisation procedure is indicated by an intermittent acoustic signal (frequency 1 sec ) emitted by a buzzer on the programming unit (table 6).
The process may be inhibited due to:
- function switch in the 0 (MANUAL) position;
- incorrect connection of the accessories (electric lock, control/safety devices);
- incorrect positioning of the programming unit mic roswitches.
N.B.:To repeat the initia lisation proc edure hold down the RESET button (fig. 11 - ref. 4) for more than 4 seconds.


## 5. 959 B-E PROG RAMMING UNIT

### 5.1 LAYOUTAND DESCRIPION



### 5.2. SEITING THE ADJ USTING TRIMMERS

The programming unit features trimmers (fig. 9 - ref. 3) which regulate the following parameters:
Timmer Vo to set the opening speed.
Setting $30 \Rightarrow 100 \%$ of the initia lisation value.
Standard setting 50\%.
Timmer Vc to set the closing speed.
Setting $30 \Rightarrow 100 \%$ of the initial lisation value.
Standa rd setting $50 \%$.
N.B.: The speed initia lisation values depend on the dimensions and the mass of the door.
Timmer To to set the pa use time (AUTOMATIC logic).
Setting from 1 to 30 seconds.
Standard setting 3 sec onds.
Trimmer Fm to set the pulling force of the operator.
Setting $60 \Rightarrow 100 \%$ of maximum value.
Standard setting 100\%.
Tum the trimmers clockwise to increase the values of the settings.
Tum the trimmers anticlockwise to reduce the values of the settings.

### 5.3. PROGRAMMING THE MICROSWTCHES (fig. 10)

The programming unit has a series of microswitches which allow the functions shown in fig. 10 to be selected.
The system is supplied with all the microswitches in the OFF position.

### 5.3.1. OVERCLOSING STROKE

Thisfunction enablesthe closed position force to be inc reased by further loading the transmission system after the door has reached the mechanic al closure end stop.
It is advisable to use this function if the door is subject to pressure caused by atmospheric agents (e.g. gusts of wind) when closed.

### 5.3.2. INITIALSATION PROCEDURE

If pulling a rtic ulated a msorsliding armsare mounted or in the eventofopening anglesof more than $90^{\circ}$, the NON-STANDARD processmust be selected. In thiscase an extemalmechanical stop must always be provided.

### 5.3.3. FUNC TION SWTCH ("O" POSTION)

Thisfunction a llowsthe operating function to be selected with the switch in the " 0 " position (see section 7 ).

### 5.3.4. PUSH AND GO

When a ctivated, thisfunction ena blesthe opening command to be given by pushing the closed doormanually. It is suffic ient to give the door an initial push in the opening direction.

### 5.4. SIGNAШNG BUZIER

The programming unit incorporates a buzzer which emits sequences of acoustic signals corresponding to different statuses of the system. The statuses that have occurred and their identific ation sequence can be seen in Table 6 .

N.B.: Press RESET after every programming operation.


Table 6: Acoustic signals

| STATUSSIGNAUED |  | ACOUSIC SEQUENCE |
| :--- | :--- | :--- |
| Connectionto mains <br> powersupply | $\prod_{\text {Pause }}^{\text {Sound }}$ |  |

The indication of error A does not inhibit the operation of the automation unit. The ind ic a tion of errorB inhibits the operation of the automation unit until the fault is eliminated.
Table 8 (paragraph 8.4) contains a list of the malfunction conditionsindic ated by the system. To identify the fault, connect the CODIS extemal programming unit (optional).

## 6. 959 MP ELEC TRONIC CONTROL UNIT

Waming: Always disconnect the electric powersupply before carrying out any work on the control unit (connection, ma intenance).


Fig. 11
(1) Fuse F1 1AT/230Vac - $5 \times 20$
(2) Terminal strip X1 ( 230 V ) - fig. 12
(3) Low voltage terminal strip X2 / X4
Description of the terminal strip
1.-2.-3. Connection offunction switch (fig. 1-ref. 12) a sshown in fig. 13.
Connection of CODIS programming unit (optional) as shown in fig. 14.
Use a $2 \times 0.5 \mathrm{~mm}^{2}$ screened cable (buscommunication) forthe connection. The screening mustbe fixed undemeath the special screws (fig. 14 - ref. 1).
Important: The maximum permissible length of the connection cable is 50 m .
To inhibit operation of the CODIS, intemupt the jumper between terminals 3 and 4 a nd installa switch (fig. 14-ref. 2).
Waming: If the CODIS is used on a continuous basis, function no. 7 must be activated at level III (see section 8). Activation of input 3 (fig. 14) enables the NIG HT or ONEWAY operating functions to be given prionty over the function selected on the CODIS unit. To select the priority function, program the CODIS suitably at level III (function no. 2 - see section 8.3). The input can be activated by means of a timer.
4. Electric lock - Common
5. Elec tric lock- N.C. contact(max. capacity $0.5 \mathrm{~A} / 24 \mathrm{~V}$ ) (fig. 15). The output is suitable for commanding a magnetic closure system. If no power is supplied, the electric lock is notactive. In the NIG HTfunction the electric lockispowered and hence active. In the event of an opening command (intemal command or EMERG ENCY OPENING), the power supply to the electric lockistemporarily cutoff to a llow the doorto be opened.
6. Electric lock-N.O.contact(max. capacity $0.5 \mathrm{~A} / 24 \mathrm{~V}$ ) (fig. 16). If no power is supplied the electric lock is a ctive and therefore guarantees-CLOSING mechanical locking. In the NIG HT function the electric lock is active even if no power is supplied. In the event of an opening command (intemal command orEMERG ENCYOPENING), the elec tric lock is temporarily powered to enable the door to be opened. In this case a reverse stroke command is also given to enable the mechanical release of the system.
7. Accessonies power supply ( +24 Vdc )
8. Accessories power supply ( 0 Vdc )
9. Intemal command: any control device (pushbutton, photocell, sensor, etc.) which, by closing a contact, can command an opening cycle of the system from inside.
10. Extemal command: any control device (pushbutton, photocell, sensor, etc.) which, by closing a contact, can command an opening cycle of the system from outside. Fig. 17 shows the control device connection. To install more than one intemal/extemal control device, connect the N.O. contacts in parallel.
Connecting microwave radar/passive infrared sensors. In the conventional configurations the control units are microwave radar and/or passive infrared sensors. To connect the FAAC sensors/radarunits equipped with a 5 pole electrical cable, refer to fig. 18.
11. Emergenc y control (fig. 19/a): a ny control de vice (normally a pushbutton) which, by opening a contact, commands an emergency closure of the system. Altematively this input can be used to command emergency opening by programming the system in a suitable manner using the CODIS programming unit (optional).
To install more than one emergency control device, connect the N.C. contacts in series.
N.B.: If emergency control devices are not connected, jumper inputs $\mathbf{1 1}$ and 15.
Activating function no. 6 at CODIS programming level III ena blesthe emergency control to be a ctivated by closing a N.O. contact.
In this case, in order to install more than one emergency control device, connect the N.O. contacts in parallel.
12. STOP safety control (fig. 19/a): any device (safety sensor, photocell, etc.) which, byopening a contact, hasa safety effect on the operating cycle. In particular, this safety device intemupts the opening/closing movement of the door.
When the safety device is disengaged, the door resumes its opening/closing movement and continues to the end of the cycle.
To install more than one STOP safety device, connect the N.C. contacts in series.
N.B.: If STOP safety de vic es a re not insta lled, jumper inputs 12 and 15.
13. CLOSURE safety command (fig. 19/a): a ny device (safety sensor, photocell, etc.) which, by opening a contact, has a safety function on the closing movement of the door. The safety device causes an immediate reversal of the closing movement of the door, but has no effect on the opening movement of the door.
To install more than one CLOSURE sa fety device, connect the N.C. contacts in series.
N.B.: If CLOSURE sa fety devicesare not connected, jumper inputs $\mathbf{1 3}$ and 15.
Connection of MINISWITCH photocells
The MINISWITC H photocellsc an be used asa safety device. For connection, see figure 19/b.
14. Accessories power supply ( +24 Vdc )
15. - 16. Acc essories power supply ( 0 Vdc )
(4) RESETbutton
N.B.: To RESET, hold down the button forat least 4 seconds.
(5) Position monitoring mic roswitch connector (fig. 1 - ref. 4).
(6) Programming unit connector (2 pole)



Fig. 12

(2)

Fig. 13
Fig. 14


Fig. 15
Fig. 16
Fig. 17

Fig. 18
Fig. 19/a
Fig. 19/b
(7) Programming unit connector (14 pole)

## 7. FUNCTION SWTCH

The 959 B-E operator has a 3-position function switch (0-1-2) mounted on one of the end covers (fig. 1 - ref. 12). This cover can be fitted on the right or the left as required (fig. 8). The switch electrical connection is shown in fig. 13.
The selectable operating functions are shown in fig. 20.


Fig. 20

## POSTION " 1 ": AUTOMATIC

When an intemal/extemal command is given, the door opens and then re-closes after the pause time.
POSTION " 0 ": MANUAL/NIGHT
The position " 0 " can be used to select two different operating functionsaccording to the programming camied out on the 959 B -E programming unit (see section 5.3 ).
The two functions are:
MANUAL: The door can be opened manually. The retum spring pulls the door closed again.
NIGH:T The extemal command is inactive. The door can be opened solely by activating the intemal command (fig. 17) or EMERGENCY OPENING (fig. 19/a) input.
POSTION "2": OPEN
When this function is selected, the door opens and remains open. The door can be closed only by activating the EMERG ENCY CLOSURE input (fig.19/ a).

## 8. "CODIS"EXTERNALPROGRAMMING UNIT(OPIIONAL)

The 959 B-E automation unit can also be controlled by an extemal programming unit in place of the function selector and of the $959 \mathrm{~B}-\mathrm{E}$ programming unit.
The CODIS (see figure 21) has four levels of operation, where the userc an select the operating functionsa nd set, programme and monitor the operation of the system.
If the CODIS is used pemanently, it is necessary to activate function 7 at Level III (programming functions): see paragraph 8.3.

For the electric al connection of the CODIS, consult figure 14. The operation of the CODIS can be inhibited in the two following ways:

- by cutting the jumperbetween terminals 3 and 4 by means of a switch (fig. 14);
- byactivating function 9 at LevelIII; in thiscase it ispossible to operate the unit temporarily after having entered code " ++--++ " by means of the " + " a nd " - " pushbuttons. After 2 minutes the CODIS will stop aga in automatic ally.

Note:the CODISc a n a lso be used asa temporary programming unit. In this case, Level II (adjusta ble functions) is ina ctive.
When the programming of the system has been completed, the CODIScan be removed: all the programmed functionswill remain unaltered.
After ha ving removed the CODIS, perform a RESETorswitch off the system.

### 8.1 LEVEL I - OPERATING FUNCTIONS

This is the level that is a c cessible to the user. By pressing either the " + " orthe "-" pushbutton, the userc an select the operating function.
Five operating functionsare available. They a re displayed on the left-hand side of the front panel of the CODIS.
When a function has been selected, the corresponding LED lights up on the front panel.
Press the " + " pushbutton to move the lighting of the LEDsone position up.
Press the "-" pushbutton to move the lighting of the LEDs one position down.
The five available functions displayed on the panel are:

o LED 6 MANUAL
The door is released and can be operated manually.
The control devices are inactive.


## o LED 5 OPEN

The dooropens and remainsopen.

## o LED 4 AUTOMATIC

The door opens when internal or extemalcommandsare active and re-closes after the pa use time.


- LED 3 AUTOMATIC (SPARE)


## o LED 2 ONE-WAY

Entry (or exit) inhibited; only one direction of exit (or entry); opening when intemal (orextemal) command is a ctive; closing after pa use time. The external (or intemal) control devices are inactive.

o LED 1
NIGHT
The doorislocked shutby the electric lock.
The extemal command is inactive. The door can be opened solely by activating the intemal command or EMERGENCY OPENING input. The door closes after the night pause time.


Fig. 21

### 8.2. LEVEL II - ADJ USTABLE FUNC TIONS

Important Levelllisa ctive only if the CODISisused permanently (function 7 of Levelllla a ctivated). The C ODISprogramming unit has one adjusting level.
Six parameters can be set. They are displayed on the righthand side of the CODIS front panel, with the relevant LEDs:

| RESET | RESET: repeat initia lisa tion process <br> (see pa ra graph 4.1). |
| :--- | :--- |
| OPENING SPEED: adjust to $30 \Rightarrow 100 \%$ |  |
| of initia lisation value. |  |
| The sta nd ard setting is $100 \%$ |  |

of the activation of the intemal/ extemal control devices. The standard setting is 2 seconds.

## Tpn」 LED 10

NIGHT PAUSE TIME: adjust to 0-30 sec onds. The opening isc ontrolled by means of the activation of the KEY/EMERGENCY OPENING commands.
The standard setting is 7 seconds.

### 8.2.1. ADJ USTMENT OF PARAMEIERS

To access Level II (adjustable functions), proceed as follows:

1) Select the parameterto be adjusted by causing the relevant LED to light up. Press the " + " pushbutton to move the lighting of the LEDsone position up. Pressthe "-" pushbutton to move the lighting of the LEDs one position down.
2) Press the " + " and "-" pushbuttons simultaneously. The LED relevant to the selected parameter will start flashing in order to give information about the stored value: if the fla shing rate is high, a high door speed or a short pa use time ha sbeen stored; if the flashing rate is low, a low door speed or a long pause time has been stored.
3) Press the " + " or " - " pushbutton repeatedly, in order to increase or decrease the flashing frequency of the LED, that is to say, to change the value of the selected parameter. When the " + " pushbutton ispressed, the door speed, opening excursion and pause time are increased. When the "-" pushbutton is pressed, the door speed, opening excursion and pause time are decreased.
4) Return to Levell (operating functions) by pressing the " + " and "-" pushbuttons simultaneously.
Notes: - The CODIS automatically retums to Level I after 2 minutes of inac tivity.

- To prevent the settings from retuming to standard values after a RESETor a voltage drop, "protect" the programmed values by activating function 18 at Level III (see paragraph 8.3).


### 8.3. LEVEL: III - PROGRAMMING FUNCTIONS

The CODIS has a programming level where certa in functions can be selected.
These functions are required for several special applic ations.
Note: a volta ge drop or a RESETcommand will not cancel the programming on Level III.
Standard programming can be restored by means of function 15 (see Table 7).
To access Level III, proceed as follows:

1) Select the NIGHToperating function by causing LED 1 to light up. Press the " + " pushbutton to move the lighting of the LEDsone position up. Pressthe "-" pushbutton to move the lighting of the LEDs one position down.
2) Press the " + " a nd "-" pushb uttons simultaneously fora bout 2 seconds, until the red ERROR LED lights up.
3) Enter the access code by pressing the " + " and "-" pushbuttons in the following sequence: "+++--+++".
Note: after the lighting up of the red ERROR LED, if the code is not entered within $\mathbf{1 0}$ seconds the CODIS will a utomatic ally retum to Level I.
4) .Select the function to be programmed by pressing the " + " or "-" pushbutton so as to obtain the combination of lit LEDs indicated in Table 7.
5) Pressthe " + " and " - " pushbuttonssimultaneously to a ctivate ordeactivate the function, and check the status of LED 6, according to the indications of Table 7.
Note: the standard programming is the one with LED 6 unlit (OFF).
6) To retum to Levell (operating functions), repeatedly press the "-" pushbutton until all the six LEDs are off, then press the " + " a nd "-" pushbuttons simultaneously.
Note: the CODIS will automatically retum to Level I after 2 minutes of inactivity.

Table 7: programming functions

| FUNCT.NO. | LEDS |  |  |  |  | FUNCTIONS | LED 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | 2 | 3 | 4 | 5 |  |  |
| 0 | OFF | OFF | OFF | OFF | OFF | Output Level III | OFF |
| 1 | ON | OFF | OFF | OFF | OFF | One-way with lock active One-way with lock inactive | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 2 | OFF | ON | OFF | OFF | OFF | NIGHT function (teminal 3-959MP) ONE-WAY function (terminal 3-959MP) | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 5 | ON | OFF | ON | OFF | OFF | Emergency closing (teminal 11-959MP) <br> Emergency opening (terminal 11-959MP) | OFF <br> ON |
| 6 | OFF | ON | ON | OFF | OFF | Emergency command - N.C. contact (teminal 11-959MP) <br> Emergency command - N.O. <br> contact (terminal 11-959MP) | OFF <br> ON |
| 7 | ON | ON | ON | OFF | OFF | CODIS - temporary connection CODIS - permanent installation | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 8 | OFF | OFF | OFF | ON | OFF | 15 kg static force 9 kg static force | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 9 | ON | OFF | OFF | ON | OFF | CODIS inhibited inactive CODIS inhibited active | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 10 | OFF | ON | OFF | ON | OFF | Standard opening pause time Immediate closing | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 15 | ON | ON | ON | ON | OFF | Restore STANDARD settings <br> Retain programmed settings | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 17 | ON | OFF | OFF | OFF | ON | TEST programme inactive TEST programme active | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 18 | OFF | ON | OFF | OFF | ON | Level II RESET active Level II RESET inactive | $\begin{aligned} & \text { OFF } \\ & \text { ON } \end{aligned}$ |
| 19 | ON | ON | OFF | OFF | ON | STANDARD intemal command (teminal 9-959MP) STEP-BY-STEP intemal command (teminal 9-959MP) | OFF <br> ON |

### 8.3.1. AVAILABLE FUNCTIONS

## function 1

One-way with lock activated: in the ONE-WAY operating function, the closed door is locked by the electric lock.
One-way with lock deactivated: in the ONE-WAY operating function, the closed door is not locked by the electric lock.

## function 2

NIGHTfunction: the activation of the input between terminals 2 and 3 (959MP) selects the NIGHT operating function, with priority over the function selected on the CODIS.
ONE-WAY function: the activation of the input between terminals 2 and 3 (959MP) selects the ONE-WAY operating function, with priority overthe function selected on the CODIS. The control panel will show which function has been selected, by means of the lighting up of LED 1 or 2.
When the input is deactivated, the operating function previously selected on the CODIS retums automatic ally.

## function 5

Emergency closing: the activation of the input between terminals 11 and 15 (959MP) controlsthe closing of the doorno matter which operating function has been selected.
Emergency opening: the activation of the input between terminals 11 and 15 (959MP) controls the opening of the door no matter which operating function has been selected.

## function 6

Emergency command - N.C. contact: to activate the input between teminals 11 and 15 (see function 5), an opening pulse of a N.C. contact is required.
Emergency command - N.O. contact: to activate the input between teminals 11 and 15 (see function 5 ), a closing pulse of a N.O. contact is required.

## function 7

CODIS - temporary connection: the CODIS can be used only initially to activate certain functions. When the external programming unit is removed, the function that has been activated remains stored. In this case, Level II is inhibited, and the settings (speed, pause times, etc.) must be performed by means of the intemal 959 B-E programming unit.
CODIS - permanent installation: the CODIS is installed pema nently; the four operating levels are all active.

## function 8

15 kg static force / 9 kg static force: this function makes it possible to change the sensitivity of the anti-crushing device.

## function 9

CODIS inhibited inactive / CODIS inhibited active: this function makes it possible to activate the CODIS electronic inhibition. In this condition, no programming can be performed at any level. To release the CODIS temporarily, press the " + " and "-" pushbuttons in the following sequence: "++--++".
This operation may be camed out fortwo puposes:

1) to change the operating function ormodify some settings at Levelli; in thiscase, after 2 minutes the CODIS inhibition will come again;
2) to remove the CODIS inhibition; in thiscase, it is necessary to access Level III a nd to disable that function.

## function 10

Standard opening pause time: the pa use time begins with the door open and the control devices (e.g., sensors) inactive.
Immediate closing: the door closes when the control devices (e.g., sensors) are inactive. In thisc ase, directional sensorsmust be used.

## function 15

Restore STANDARD settings / Retain programmed functions: this function makes it possible to check whether a ny function has been programmed differently from the sta nda rd settings. If at least one function ha sbeen programmed differently from the standard settings, LED 6 is lit (ON).
In this case all the standard settings can be restored by pressing the " + " and " - " pushbuttons simultaneously.
After this operation, it is a dvisable to perform a RESET.

## function 17

IESTprogramme inactive/active: thisfunction makesit possible to ac tivate consec utive operating cyc les. The controldevices, in a ny case, take prionty overthe operation of the system. The programme can be cancelled by performing a RESET.

## function 18

Level II RESETactive / inactive: thisfunction ma kesit possible to preserve the settings of the opening, closing and opening excursion speedseven in case of a voltage drop or RESET.

## function 19

STANDARD intemal command: the activation of the intemal control device controls a complete door cycle (standard operation).
STEP-BY-STEP intemal command: the a ctivation of the intemal controldevice controlsa sequence ofdooropening / stopping / closing / stopping / opening, and so on.

### 8.4. LEVEL IV - SELF-DIAGNOSIS

The CODISprogramming unit ha sa self-dia gnostic level, which, in case of a fault, intemupts the display of the operating function every 2 seconds in order to display the malfunction condition for 0.5 sec onds. The type offault can be identified by observing the combination of LEDs 1-5 that a re lit toge therwith the red ERROR LED (see Table 8).

## Table 8

| NO. | LEDS |  |  |  |  | FAILURE | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | 2 | 3 | 4 | 5 |  | (*) |
| 1 | ON | OFF | OFF | OFF | OFF | Motor fault | B |
| 2 | OFF | ON | OFF | OFF | OFF | Govemor and brake fault | B |
| 3 | ON | ON | OFF | OFF | OFF | Initialisation process not possible Opening angle insufficient | B |
| 4 | OFF | OFF | ON | OFF | OFF | Initialisation process not possible Opening angle excessive | B |
| 5 | ON | OFF | ON | OFF | OFF | Friction or spring load excessive | B |
| 6 |  |  |  |  |  |  |  |
| 7 | ON | ON | ON | OFF | OFF | Motor overload | B |
| 8 | OFF | OFF | OFF | ON | OFF | Encoder fault (disconnected or in short circuit) | B |
| 9 | ON | OFF | OFF | ON | OFF | Cut-off relay fault | B |
| 10 | OFF | ON | OFF | ON | OFF | EPROM / RAM / relay fault (automatic control) | B |
| 11 | ON | ON | OFF | ON | OFF | Short circuit on 24 V (959MP electronic control unit or extemal) | B |
| 12 | OFF | OFF | ON | ON | OFF | Monitoring microswitch fault | A |
| 13 | ON | OFF | ON | ON | OFF | Electric lock fault | B |
| 14 | ON | ON | ON | ON | OFF | Power supply insufficient (<140 V) | B |
| 15 | OFF | OFF | OFF | OFF | ON | Microprocessor fault | B |
| 16 | ON | OFF | OFF | OFF | ON | Incorrect "door closed" position | A |
| 17 | OFF | ON | OFF | OFF | ON | Microprocessor alam | B |
| 18 |  |  |  |  |  |  |  |

(*) A: this error condition does not inhibit the operation of the system.
B: thiserrorcondition inhibitsthe operation of the a utomation unit until the fault has been eliminated.

## 9. MAINTENANCE

It is advisable to check the automation unit once a year, in orderto make sure that the dragging system and closing spring are in perfect working order.
Drive system (fig. 1 - ref. 7)
Check the toothed wheels and, if necessary, lubric ate them with grease for gears or bea rings TRIBOTECH VIP 473.
Important never use spray lubricants.

## END-USER GUDE

## 959 B-E Automation Systems

Read the end user guide carefully before using the product and keep it in a safe place for future reference.

## G ENERALSAFIY REGULATIONS

When correctly installed and used, the 959 B-E a utomatic unit assures a high level of safety. A few simple rules should be followed to prevent problems from arising a ccidentally:

- Do not stand orallow child ren or adultsto stand within range of the door, especially during operation, and do not leave objects nearit.
- Do not allow children to play with the door.
- Do not deliberately obstruct movement of the door.
- Keep the "a utomatic door" signs effic ient and clea lly visible.
- In the event of a malfunction, select MANUAL OPERATION and wait fora qualified technic ian to perform the necessary repair work.
- Do not modify the components of the a utomatic unit.
- Do not attempt to repairthe automatic unitorto perform any operation on it. Call qualified FAAC technicians only.
- At least once every 6 monthsha ve qua lified personnel check thatthe a utomatic unit, safety devicesand earth connection are in working order.


## DESCRIPIION

The 959 B-E automatic unit for swing doors is a one-piece unit consisting of an electromechanical device that allows door opening to be controlled by means of a driving arm. The door is re-closed by a spring system.
The operatorcan be installed eitheron the lintel or on the door structure itself.
The stainlesssteel protective casing housesthe electronic control unit used to program and control the operation of the system.
The a utomatic unit 959 B-E hasa selector which can be used to choose the operating logic shown in fig. 1. A CODIS programming unit (fig. 2) can be installed asan altemative to the function selector, in which case the following operating functions are available:

## OPERATING FUNCTIONS



## o LED 6 MANUAL

The door is released and can be operated manually. The control devices are inactive.

## o LED 5 OPEN

The dooropensand remainsopen.

## - LED 4 AUTOMATIC

The door opens when intemal or extemalcommandsare active and re-closes after the pause time.

## - LED 3 AUIOMATIC (SPARE)

- LED 2 ONE-WAY

Entry (or exit) inhibited; only one direction of exit (or entry); opening when intemal (orextemal) command is a ctive; closing after pa use time. The external (or intemal) control devices are inactive.

## o LED 1 NIGHT

The door is locked shut by the electric lock.
The external command is inactive. The doorcan be opened solely by activating the intemalcommand or EMERGENCY OPENING input. The door closes after the night pause time.

The different logic modesare active when the corresponding LED is illuminated steadily. To change the operating function press the +or-control button.

## MANUAL OPERATION

If the door has to be activated manually due to failure of the electrical powersupply ora malfunction of the a utomatic unit, proceed as follows:

Function selector

- Tum the selector to the "0" MANUAL/NIG HT position
- Open or close the door manually

CODIS unit

- Pressthe +button to set the operating function to the manual position with LED 6 lit steadily.


## RETURN TO NORMAL OPERATION

Function selector

- Tum the function selector to the " 1 " AUTOMATIC position.


## CODIS unit

- Press the - button to set the operating function in the desired position (LED lit steadily). See fig. 2.



## POSITION "1": AUIOMATIC

When an internal/extemal command is given, the door opens and then re-closes after the pause time.
POSITION "0": MANUAL/NIGHT
The position " 0 " can be used to select two different operating functionsaccording to the programming camied out on the $959 \mathrm{~B}-\mathrm{E}$ programming unit. The two functions are:
MANUAL The door can be opened manually. The retum spring pulls the door closed again. NIGHT: The extemal command is inactive. The door can be opened solely by activating the intemal command or EMERGENCY OPENING input. POSITION " 2 ": OPEN
When this function is selected, the dooropens and remains open. The door can be closed only by activating the EMERGENCY CLOSURE input.


