

# EC MACHINE DIRECTIVE COMPLANCE DECLARATION 

## (DIRECTIVE 89/392 EEC, APPENDIX II, PARTB)

## Manufacturer:

FAAC S.p.A.
Address:
Via Benini, 1-40069 Zola Predosa BOLOGNA - ITALY

Hereby declares that the 565/570/575 a utomation system

- is intended to be incorporated into machinery, or to be assembled with other machinery to constitute machinery in compliance with the requirements of Directive 89/392 EEC, a nd subsequent amendments 91/ 368 EEC, 93/44 EEC and 93/68 EEC;
- complies with the essential safety requirements in the following EEC Directives:

73/23 EEC and subsequent amendment 93/68 EEC.
89/336 EEC and subsequent amendments 92/31 EEC and 93/68 EEC.
and furthemore declaresthat unit must not be put into service until the machinery into which it is inc orporated or of which it is a component has been identified and declared to be in conformity with the provisions of Directive 89/392 EEC and subsequent amendments enacted by the national implementing legislation.

Bologna, 1 J anuary 1999


## IMPORTANT NOTICE FOR THE INSTAUER <br> GENERALSAFETY REGULATIONS

1) IMPORTANT! FAAC strongly recommends to follow these instructions carefully for the safety of persons. Improper installation or misuse of the product will cause very serious damages to persons.
2) Read the instructionsc arefully before installing the product.
3) Packaging materials(plastic, polystyrene etc.) are a potentialhazard and must be keptoutofreach of children.
4) Keep these instructionsforfuture reference.
5) This product has been designed and manufactured only forthe use stated in thismanual. Any otheruse notexpressly set forth will affect the relia bility of the productand/orcould be source of hazard.
6) FAAC S.p.A. cannot be held responsible forany damage caused by improperuse ordifferentfrom the use forwhich the a utomation system is destined to.
7) Do not use this device in areassubject to explosion: the presence of flammable gasorfumesisa serioushazard.
8) Mechanic alconstructive elementsmustcomply with UNI8612, CEN prEN 12604and CEN prEN 12605 standards

Countriesoutside the EC shallfollow the regulationsabove besidestheir nationalnomative referencesin orderto offerthe utmostsafety.
9) Fa ac cannotbe held responsible forfailure to observe technic alstandardsin the construction of gatesand doors, orforany deformation of the gateswhic $h$ may oc curduring use.
10) Insta llation must comply with UNI8612, C EN prEN 12453 a nd CEN prEN 12635.

The degree of sa fety of the a utomation must be C + D.
10A) IEC 335-2-95
11) Before attempting any job on the system oroperator, cut outelectric powerand disconnect the batteries, if installed
12) Anomnipowerswitc $h$ shall be provided forthe installation with a n opening distance of the contacts of 3 mm of more. Altematively, use a 6A
thermomagnetic breakerwith multi-pole switc hing.
13) Ensure that there is differential switc h up-line of the electric al system, with a trip threshold of 0.03 A .
14) Checkthat the earthing plantisin perfectcondition and connectitto the metallic parts. Also earth the yellow/green wire of the operator.
15) The automation isfitted with a n anti-c rush sa fety system that isa torque controldevice. In anycase, furthersa fetydevic esshallbe installed.
16) The safety devices(e.g.photocells, safety edges, etc.) protectareas where there isa mechanic almovementhazard, e.g.crushing, entrapmentand cutting
17) Each installation mustbe fitted with a tleastone fla shing light(e.g. FAAC LAMP, MINILAMP, etc.) a swell asa wa ming plate suitably fixed to the gate, besidesthe safety devic esasperpoint 16 above.
18) Faac cannotbe held responsible regard ing safetyand correctfunctioning of the automation in the event that partsotherthan Faac original partsare used.
19) Use only Faac originalspare partsforma intenance operations.
20) Do notcamyoutany modific ationsto automation components.
21) The insta llermustsupply a llinformation rega rding ma nual operation of the system in the eventofanemergencyand provide the end-userwith the "End-userG uide" attached to the product.
22) Do nota llow children oradultsto sta nd nearthe productduring operation.
23) Keep out ofreach of childrenthe remote radio controlsand a nycontrol devices. The automation could be operated unintentionally.
24) The end-usermustavoid any attemptto repairoradjust the automation personally. These operationsmustbe carmed outexclusively byqualified personnel.
25) What is not explicitly stated in these instructions is not permitted.

## AUIOMATIC SYSTEM 565/570/575

These instructionsapply to the following models:

## 565-570-575

Automa tic systems565-570-575 are designed to automate overhead spring-balanced, sectional, and counterbalanced (with speciaIGDA 3000 a c cessory) doorsforresidentia Iga rages.
Theyconsistofan elec tro-mec hanic a loperator, electronic control applia nc e a nd c ourtesy la mp built into a sing le unit. The unit is fitted to the ceiling and opens the door by means of a transmission chain.
The system is non-reversing and, therefore, the door locksmechanic a lly when the motorisnot operating a nd, consequently, no otherlockisnecessary; two ma nual relea seson the inside and outside (optional) make it possible to move the doorma nually in case of a powercut orfault.
Any obstacles are certain to be detected by a controlling electronic device which comesinto a ction while the automatic system is in operation.
The 565-570 and 575 automated systemswere designed and built forindooruse and forc ontrolling vehic le ac cess.Avoid any other use.

## 2. DIMENSIONS



Dimensionsin mm
Fig. 1

## 1. DESCRIPIION AND TECHNICALSPECIRCATIONS

| MODEL | 565 | 570 | 575 |
| :---: | :---: | :---: | :---: |
| Power supply | 230 V ac 50Hz |  |  |
| Electric motor | 24 V dc |  |  |
| Maximum absorbed power | 220W |  |  |
| Maximum cycles per hour | 20 (with load of 56 Kg at $20^{\circ} \mathrm{C}$ ) |  |  |
| Maximum consecutive cycles | 6 (at $20^{\circ} \mathrm{C}$ ) |  |  |
| Minimum distance from ceiling | 35mm (Fig.4 and 5) |  |  |
| Maximum available travel | 1900mm | 2500 mm | 3100 mm |
| Pulling/thrust power | $1200 \mathrm{~N}(\sim 120 \mathrm{Kg})$ |  |  |
| Courtesy light | 230 V ac 40W max |  |  |
| Courtesy light timer | 2 minutes |  |  |
| Camiage speed (load free) | $12 \mathrm{~cm} / \mathrm{sec}$. |  |  |
| Deceleration speed | $6 \mathrm{~cm} / \mathrm{sec}$. |  |  |
| Deceleration travel | Varies according to setup |  |  |
| Intemal safety device | Type 2 |  |  |
| Response time of built-in safety device | 150msec |  |  |
| Door max width | 3000 mm ( 5000 mm sectional) |  |  |
| Door max height | See maxavailable travel |  |  |
| Protection class | IP20 |  |  |
| Ambient temperature | $-20 /+55^{\circ} \mathrm{C}$ |  |  |

## 3. ANCILARY EEC TRICALEQUIPMENT


(1) Cable $2 \times 0,5$ (TX photocell)
(2) Cable $4 \times 0,5$ (RX photocell)
(3) Cable $3 \times 0.5$ (Radio receiver)
(4) Power pipe (230V)
(5) Low voltage pipe
(6) Cable $2 \times 1.5+$ earth (power supply)

## 3. DESCRIPION



## 4. PRELMINARY CHECKS

The struc ture of the doormust be suitable foraccommodating automation. In partic ular, checkthat the doordimensionsconform to those indic ated in the tec hnic al specific ations, and that the doorissuffic iently sturdy.
Check the effic iency of the doorbearingsand joints.
Make sure the doorisfree of any friction; ifnecessary, clean the guidesa nd oil them with silic one lubric ant, but do not use grease. Remove the door' sexisting closing mechanism to ensure the doorisclosed by the a utomatic system.
Checkif an effic ient earth plate is a vailable forelectricalconnection to the operator.
Make sure there is a clearance of at least 35 mm between the ceiling and the highestsliding point of the door(fig. 4 and 5 ).
In the case of sectionaldoors, checkthat the upperguide rollerisin the horizontalpartof the guide when the doorisclosed (fig.6).


## 5. OPERATORASSEMBLY

N.B.: Screws and expansion plugs forsec uring the operator to the infrastruc ture are notsupplied.
5.1 If using the outside release device (optional item), withdraw the camiage from the guide, and fitthe cable in the appropriate seat on the cariage, as shown in figure 7.
5.2 Fit the guide (Fig. 8 ref.B) in the slide (Fig.8ref.C), centrally with respect to the slide.Pre-form the bracketsa nd secure them to the guide with the nut (Fig.8).
5.3 Insert the longitudinal member with chain in the central slide (fig. 9) until it meetsthe metal projection (fig. 8 ref.D).

5.4Fita new longitudinalmember(fig.10) in the a lready installed unit, making sure that the metalprojection shown in Fig. 8 ref.A comes into contact with the central slide.
5.5 Remove the housing, unscrew the lamp and, using a suita ble wrench, remove the nutssecuring the motorunit to the operator (fig.11).

5.6 Offer the a ssembled guide to the operator.
5.7 Lift up the motorunit, ta king care not to damage the control board, couple the cha in to the pinion gear (fig.12).
5.8 Locate the drive unit on the support, securing it with a ppropriate self-tapping screws(Fig. 13 ref.A).Fit the longitudinalmember a sin figure 13 (ref.A) to itsstop point.
5.9 Tighten the drive unit with the appropriate wrench (fig. 13 ref.B).

5.10 Fit the flange into the sliding guide, securing it with the two supplied M5Allen sc rews(fig.14), a nd a pply tension to the cha in with the nut (fig.14).
5.11 Position the operatoronthe ground, vertic a lly respectto floor (fig. 15 ref. A).
5.12 C heckchaintension, making sure thatthese distancesa re equal(asshown in fig. 15 ref. B) : lowercha in-upperchain; upper cha in - upper rail joint.
5.13 Adjustc haintension if necessary, using the nut asind ic ated in fig. 15 ref. C.
N.B. : To apply tension to the chain, tum the nut clock - wise.

To slacken the chain, tum the nut anti clock - wise
Waming: too much chaintension could damage the motorunit.



## 6. INSTALATION

6.1 Find the mid-point of doorand ceiling and mark the two lines with a hig hlighter.
6.2 Find the highest movement point of the doorand mark this on the lintel.
6.3 Position the securing bracket 5 mm above the line you had marked, which must be centered with respect to the door(fig.16). 6.4 Mark the two bracket securing points and drill the necessary holes.
6.5 Next, using screwsand washers, sc rew the bracket on the expansion plugs(fig. 16).

6.14 Place the knot inside the knob - asshown in fig. 20 ref. Ba nd close it.
6.15 If using the centralsupport guide, shape the brackets, lock them with a nut and secure them to the ceiling (fig. 21).
6.6 Place the operatoron the ground, lift up the slid ing longitudinalmemberand step toward the bracket - fit the screw and tighten the nut (fig. 17).
6.7 Lift up the operator, making sure it ishorizontal with respect to the door-use a spint level.
6.8 When you have reached the correct position, measure the dista nce between ceiling and operatorso that you can shape the securing bracketsin advance.
6.9 Fit the supplied bracketsin the slotsand secure the operator with the nut (fig. 18).
6.10 Bend the sec uring brackets in line with the measurements you had taken (fig. 19).
6.11 Lift up the operator, place it in itsc orrectposition, a nd mark the securing holes.
6.12 Drill, insert the expansion plugs and, using screws and washers, secure the motor unit to the ceiling (fig. 20 ref. A).
6.13 Firstestablish the height of the release knob, cutoff excess cord, and make a knot on the cord end.

6.16 Forsectionaldoors, see point 6.25.
6.17 Secure the attachment to the drive shaft, using a suita ble screw and nut (fig. 22).
6.18Release the operator, by pulling the release leverdownward (fig.23).
6.19 C lose the overhead door.
6.20 Take the released carmiage to the closing point.
6.21 Rest the attachment on the door, in a central position with respect to the mid-line you had marked out.
N.B.: The distance between drive bracketand sliding rail bracketmustnotexceed $\mathbf{2 0} \mathbf{c m}$ ( $\mathbf{m a x} \mathbf{3 0 ^ { \circ }}$ ) (fig.24).
6.22 Check the position, drill a nd secure with suita ble screws(fig.24).

6.23 Re-lock the automatic system by pulling the ha ndle sideways(fig.25) N.B.: on release, make sure you can see the red "LOCK" ind ic ation window underthe camiage - thismea nsit wascorrectly reset.
6.24 Important: slide the door along the rail to re-locate the hook-up point.
6.25 Forsectional do orsthat require it, fit the arm shown in figure 26 ref. A on the attachment and camy on from point 6.18.


## 7. CONNECTION OF565 MPSELEC TRONIC CARD

## IMPORTANT: Before attempting any work on the card (connections, programming, maintenance), alwaystum off power.

Observe points 10, 11, 12, 13 a nd 14 of the GENERALSAFETY RULES.
Observing the ind ic ationsin fig. 2 , install the racewa ysand make the elec tric a Iconnec tionsfrom the 565 MPSelec tronic applia nce to the selected ac cessories(fig. 28).
Alwaysseparate powercablesfrom controland safety cables(push-button receiver, photocells, etc.). To preventany electric noise whatever, use separate sheaths.

## TECHNICALSPECIPCATIONS

| Power supply voltage | 230 V ac 50 Hz |
| :--- | :--- |
| Power supply for accessories | 24 Vdc |
| Accessories max. load | 200 mA |
| Ambient temperature | $-20^{\circ} /+55^{\circ} \mathrm{C}$ |
| Fuses | transf./motor primary <br> wind ing |
| Quick-fit connector | for decoding cards and <br> RPreceivers |
| Function logics | Automatic/Semi- <br> a uto matic |
| Temminal board connections <br> safe/ <br> Flashlight | Open/Stop/Sa fety <br> devic es/Fail- |



## DESCRIPION

## TERMINALBOARDJ 1 (low voltage)

## OPEN=OpenCommand (N.O.)

Any device (push-button, detector,...) which, by closing a contact, supplies an opening (orclosing) pulse to the door.
To install several Open devices, connect N.O. contacts in parallel.

## STOP=Stop command (N.C.)

Any device (e.g. a push-button) which, by opening a contact, stopsdoormovement.
To install severalstop devices, connect the N.C. contacts in series.
N.B.: ifstop devic es are notused, jumperc onnectSTOP to the inputs c ommon contact

- input/negative accessoriessupply commoncontact.
( $=$ Accessories supply positive pole ( 24 V dc 200 mA max)


## FSW=C losing safety-devicescontact(N.C.)

Safety devicesare alldevices(photoc ells, sensitive edges,...) with N.C. contact, which, if there isan obstacle in the area they protect, operate to reverse doorclosing movement.
If the sa fety devic es are activa ted when the doorislocked oropen, they prevent it from closing.
To install several sa fety devices, c onnect the N.C. contacts in series.
N.B.: ifsafety devic esare notc onnected, jumperc onnectFSWto the inputs common contact
-FSWTX=Terminal forconnection of the negative pole (-) of the photocellstransmitter(TX).
CONNECTORJ 2 (lowvoltage)
Connector) 2 is used forrapid connection of MINIDEC, DEC ODER, and RP REC EIVER cards.
Insert and remove the cardsaftercutting power.

## TERMINALBOARDJ 3(high voltage)

Terminal board forpowersupply of $230 \mathrm{~V} \sim 50 \mathrm{~Hz}$ ( $\mathrm{F}=$ phase $\mathrm{N}=$ neutral)
C onnect the system'searth wire to the dedic a ted terminal(see ID sticker- fig. 31 ref.A).

## TERMINALBOARDJ 6 (high voltage)

230V~Termina l board forconnection of fla shlight.

## K1 J UMPER (enable/disable fail-safe)

The 565 MPSca rd hasanothersa fety device - the FAIL-SAFE- whic h, priorto any activation, controlsif the N.C. contact on the photocellreceiver(fig.27) iso perating effic iently.

## JUMPERLK2(150N/ 300N)

Servesto vary the sensitivity of the reversing device (fig. 27).


## 8. ANTENNA INSTAШATION(OPIONAL)

8.1 If you are using an RP receiver, a nd wish to inc rease itsrange, you can use an extemal433 MHZantenna (antenna connection instructions are on the rearof the RP receiverblister-pack).
8.2 Pic k up the housing and, using an a ppropriate bit, drill from the inside outward in the guided area (fig. 29).
8.3 Turn the housing toward the front, fit the antenna and secure it from the inside with a suitable nut (fig. 30).


## 9.CONNECTIONS

9.1 Connect the powercable, asshown in figure 31, securing it with a clamp in the indic ated area.


## 10. PROGRAMMING

To accessthe programming push-button, dismantle the courtesy light ceiling fixture, unsc rewing the appropriate sc rew. Slide the ceiling fixture in the direction shown by the a mow (fig.34).

## SET-UP CYCLE

During this procedure, the obstacle detection and Fail-safe device are NOToperating.
The set-up cyc le defines:

- anti-c rushing safety levelsduring opening a nd closing
- deceleration points
-doorcomplete opening a nd closing point
- pause time

Thisproc edure can be camed outatany time, with the operator in a nyposition, by meansofthe set-up push-button (see different set-up modes).
Set-up occurswith a max. force of 800 N . Ifthe force isnotsufficient to complete the leaming, it can be increased to 1200 N by activating, during the 800 N cycle, a second set-up procedure (by pressing the set-up push-button again asindicated in the differentmodes).
Two function logic sare available on thisa ppliance:
AUTOMATIC (TABLE1)
SEMI-AUTOMATC (TABLE2)

9.2 Fit the screw in the approp riate seat and tig hten with wa sher and nut (fig. 31 ref.A).
9.3 Position the earth eyelet on the screw, add a washerand tighten wit the nut (fig. 32 ref.A).
9.4 Ifyou are using tube sleevesto sec ure the cables, make a slot asshown in figure 32.
9.5 Sc rew the la mp in the appropriate la mp-holder.
9.6 Sec ure the operatorhousing using a ppropriate screws(fig.33).


## AUIOMATIC SET-UP

The set-up procedure isexec uted a utomatic a lly justwith a pulse.

## MANUALSET-UP

Thisprocedure ena blesyou to selectthe deceleration points, the fully open point, and pa use time.

## AUIOMATIC SET-UPWTHLOGIC "E"(SEMI-AUIOMATIC)

Press a nd relea se the SET-UP push-butto n to select the logic.
After8sec ondsthe operatoreffectsa closing operation untila stop isdetected.
The operatornow opensthe door, and the opening movement finisheswhen the mecha nic alstop is recognised.
The doorisimmediately closed.
The electronic a pplia nce establishesthe deceleration points. If the SEIUP proced ure wa ssuc cessful, the c ourtesy la mp sta ys lighted for5 sec onds. During thistime, in orderto reduce the load on the relea se system, open pulsesc an be sent within 2 sec onds of each other to reverse the release carriage. A pulse equals tra velof 5 millimetres.
N.B.: the carriage can be seen to reverse only when the automated system isoperating nomally.

## MANUALSET-UPWTHLOGIC "E"(SEMI-AUTOMATIC)

Pressa nd relea se the SET-UP push-button to select the logic.C a my out the following procedure within 8 sec ond safterpressing the SETUP push-button, otherwise the oprator will execute a utomatic SETUP.
$1^{\text {st }}$ OPEN: the opera toreffectsa closing operation until a stop is detected.
2nd OPEN: the operatorcontinueswith an opening movement. 3rd OPEN: defines the point at which start of deceleration is required.
4th OPEN: definesthe end of the opening** movement.
5th OPEN: startsclosing movement.
6th OPEN: defines the point at which sta rt of deceleration is required.
Allow the operatorto reach the stop.
If the SETUP proced ure wa ssuc cessful, the c ourtesy la mp sta ys lighted for5 sec onds. During thistime, in orderto reduce the load on the relea se system, o pen pulsesc an be sent within 2 sec onds of each other to reverse the release carriage. A pulse equals tra velof 5 millimetres.
N.B.: the carriage can be seen to reverse only when the automated system isoperating nomally.

## AUIOMATIC SET-UPWTHLOGIC "A"(AUIOMATIC)

Hold down the SET-UP push-button to select the logic until the c ourtesy light goeson (about 5 seconds).
After8sec ondsthe operatoreffectsa closing operation untila stop is detec ted.
The operatornow opensthe door, a nd the opening movement finisheswhen the mechanic alstop isrecognised.*
The doorisimmed iately closed.
The electronic appliance esta blishes the deceleration points, a nd pause time isfixed at 3 minutes.
If the SEIUP proced ure wa ssuc cessful, the c ourtesy la mp sta ys lighted for5 sec onds. During thistime, in orderto reduce the load on the relea se system, open pulsescan be sent within 2 sec onds of each other to reverse the release carriage. A pulse equals tra velof 5 millimetres.
N.B.: the carriage can be seen to reverse only when the a utomated system isoperating normally.

## MANUALSET-UPWTHLOGIC "A"(AUIOMATIC)

Hold down the SET-UP push-button to select the logic until the courtesylightgoeson (a bout 5 sec onds).C a my out the following procedure within 8 sec ond sa fterpressing the SEIUP push-button, otherwise the opratorwill execute a utomatic SEIUP.
$1^{\text {st }}$ OPEN: the operatoreffec ts a closing operation until a stop is detected.
2nd OPEN: the operatorcontinueswith a n opening movement. 3rd OPEN: defines the point at which start of deceleration is required.
4th OPEN: definesthe end ofthe opening movement and starts the pa use time count** ( 3 minutesmax.).
5th OPEN: intemuptsthe pause time count a nd sta rtsthe c losing movement.
6th OPEN: defines the point at which start of deceleration is required.
Allow the operatorto reach the stop.
If the SETUP proc edure was suc cessful, the courtesy la mp sta ys lighted for5 sec onds. During thistime, in orderto reduce the load on the relea se system, open pulsesc an be sentwithin 2 sec onds ofea ch otherto reverse the relea se ca mia ge. A pulse equalstravel of 5 millimetres.
N.B.: the carriage can be seen to reverse only when the a utomated system isoperating nomally.

* Otherwise, an OPEN pulse may replace the stop.
** Otherwise, the stop can be used during opening.

IMPORTANT: Atset-up, ifthe operatordoesnoteffec tany movement when the OPEN push-button (see fig. 34 ref. $A$ ) is pressed, check that the housing is in correct position.

## FUNCTIONLOGICS

Ta ble 1AUTOMATIC Logic

| OVERHEAD <br> DOOR | OPEN | STOP | SAFETY DEVICES |
| :---: | :---: | :---: | :---: |
| CLOSED | Opensand <br> closes afterthe <br> pause time | No effect** | No effect |
| OPEN FOR <br> PAUSE | Restartspause <br> time count* | Locks* | Restartspause <br> time count* |
| CLOSING | Reversesmotion | Locks** $_{\text {Reversesmotion }}^{\text {Rever }}$ |  |
| OPENING | No effect | Locks** | No effect* |
| LOC KED | Closes | No effect** | No effect* |

Table 2 SEMI-AUTOMATIC Logic

| OVERHEAD <br> DOOR | OPEN | STOP | SAFEIY DEVICES |
| :---: | :---: | :---: | :---: |
| C LOSED | Open | No effect** | No effect |
| OPEN | Closes | No effect** | No effect* |
| CLOSING | Reversesmotion | Locks** | Reversesmotion |
| OPENING | Locks | Locks** | No effect* |
| LOC KED | Closes | No effect** | No effect* |

* Preventsclosing if pulse is maintained
* Prevents closing and/oropening if pulse is maintained

When installation hasbeen completed, check the effic iency of the automated system and safety devices, and then apply the "danger" wa ming sticker(fig.35) on the panel of the up-and-overdoorto make it easy to see.
Applythe sticker, which indicatesthe release device of the automated system (fig.35).

## 11. OPTIONALACCESSORIES

- If you are using the card for the CN60-E Sensitive Edge, a compartment isprovided foritinside the operatorhousing in the position shown in figure 36.
- Floating batteriesinstallation procedure: fit them on the operator with the a ppropriate bracket, and secure them with screw and nut in the position shown in figure 37.
ATIENTION! If repla cing batteries, c ut outelectric al power before attempting a ny operation.


## AWARNING




- Two extemal release systemsca n be fitted:
- with ha ndle (fig. 38 ref.A)
- with wrench (fig. 38 ref.B)
- Counterbalanced doors can be automated by using the accessory shown in fig. 39 (GDA 3000).



## USER'S GUIDE

## AUIOMATIC SYSTEMS 565-570-575

## Read the instructions carefully before using the productand store them forfuture use.

## GENERALSAFETY REGULATIONS

If correctly insta lled a nd used, 565-570-575 a utomatic systemsensure a high degree of safety.
Some simple ruleson beha viourcan preventaccidental trouble:

- Do not, underany circ umstances, stand underthe overhead door.
- Do not allow children, personsorthingsnearthe a utomatic systems, espec ially while they are operating.
-Keep remote-controls, orotherpulse generatorsthatcould open the door, well away fromchildren.
- Do not allow child ren to play with the a utomatic system.
-Do not willingly obstruct doormovement.
- Prevent any branchesorshrubsfrom interfering with doormovement.
- Keep the indicator-lightseffic ient and easy to see.
- Do not attempt to activate the door by ha nd unless you have released it.
- In the event of malfunctions, relea se the doorto allow access and wait forqualified tec hnic al personnel to do the necessary work.
-When you ha ve set ma nualoperation mode, cutpowerto the system before restoring nomaloperation.
- Do not in a ny way modify the components of the automation system.
- Do not attempt any kind of repairordirect action whatever and contact qualified FAAC personnelonly.
- At least every six months: a range a check by qualified personnel of the automatic system, safety d evic esa nd earth connection.


## DESCRIPTION

Auto ma tic systems565-570-575 a re designed to automate overhead spring-ba lanced, sectional, counterbalanced (with special GDA 3000 a ccessory) doors forresidential garages.
The automatic systemsc onsist of an electro-mec ha nic al operator, elec tronic control a ppliance, courtesy lamp and protection housing built into a single unit.
The system isnon-reversing and, therefore, the doorlocksmec ha nic a lly when the motor isnotoperating and, consequently, no otherlockisnecessary; a ma nualrelease makes it possible to move the door in case of a powercut orfault.
An electronic device ensuresthat a ny obstaclesare detected.
The door is nomally closed; when the electronic control unit receives an opening command from the remote c ontrol, orfrom anyothertype ofpulse generator(fig.1), it activatesthe electric motorwhich, by means of a transmission chain, pullsthe door open to allow access.
-If the automatic mode was set, the doorcloses automatic a lly after pause time has elapsed.
An opening pulse supplied during opening has no effect.
-If the semi-automatic mode wasset, a second pulse must be sent to close the door again.
An opening pulse supplied during opening stopsmovement.
Anopening pulse supplied during re-closing, alwayscausesmovementto be reversed. A stop pulse (if supplied) alwa yssto psmovement.
Forfull deta ilsof doora ctivity in the different logics, c onsult the installa tion engineer.
Automatic systemsmay include safety devic es(photocells) that prevent the doorfrom c losing when there is a n obstacle in the area they protect.
Emergency manualopening ispossible by using the release system.
The wa ming-light indic atesthat the door isc urrently moving.
The courtesy light is ac tiva ted when the motor startsa nd continuesforabout 2 minutes afteritstops.

## MANUAL OPERATION

The 565-570-575 operato rsare equip ped with a n emergency system activated from the inside - however, a lockc an be fitted on request, foractivating release from the outside.
If the doorhasto be moved manually due to a powercutora fault of the automatic system, use the release devic e a sfollows:

- Release the operator, by pulling the release leverdownward (fig. 22 ref.A).


## RESTORING AUTOMATIC OPERATION MODE

Re-lock the a utomatic system by pulling the handle sideways(fig. 2 ref.B):
N.B.: on release, make sure you can see the red "LOCK" indic ation window underthe carriage - thismeansit wa scorrectly reset.
Important: slide the dooralong the rail to re-locate the hook-up point.

## LAMP REPLACEMENT (fig.3)

To replace the lamp, unsc rew and remove the ceiling fixture supportsc rew. Slide the c eiling fixture in the direction shown by the a rrow (fig.33).
Replace the lamp (220Vac , 40W max.).


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